

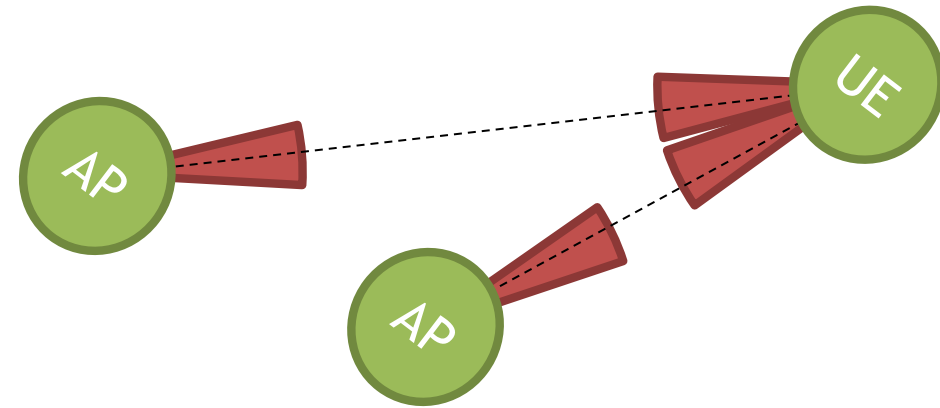
# JADE: Zero-Knowledge Device Localization and Environment Mapping for Millimeter Wave Systems

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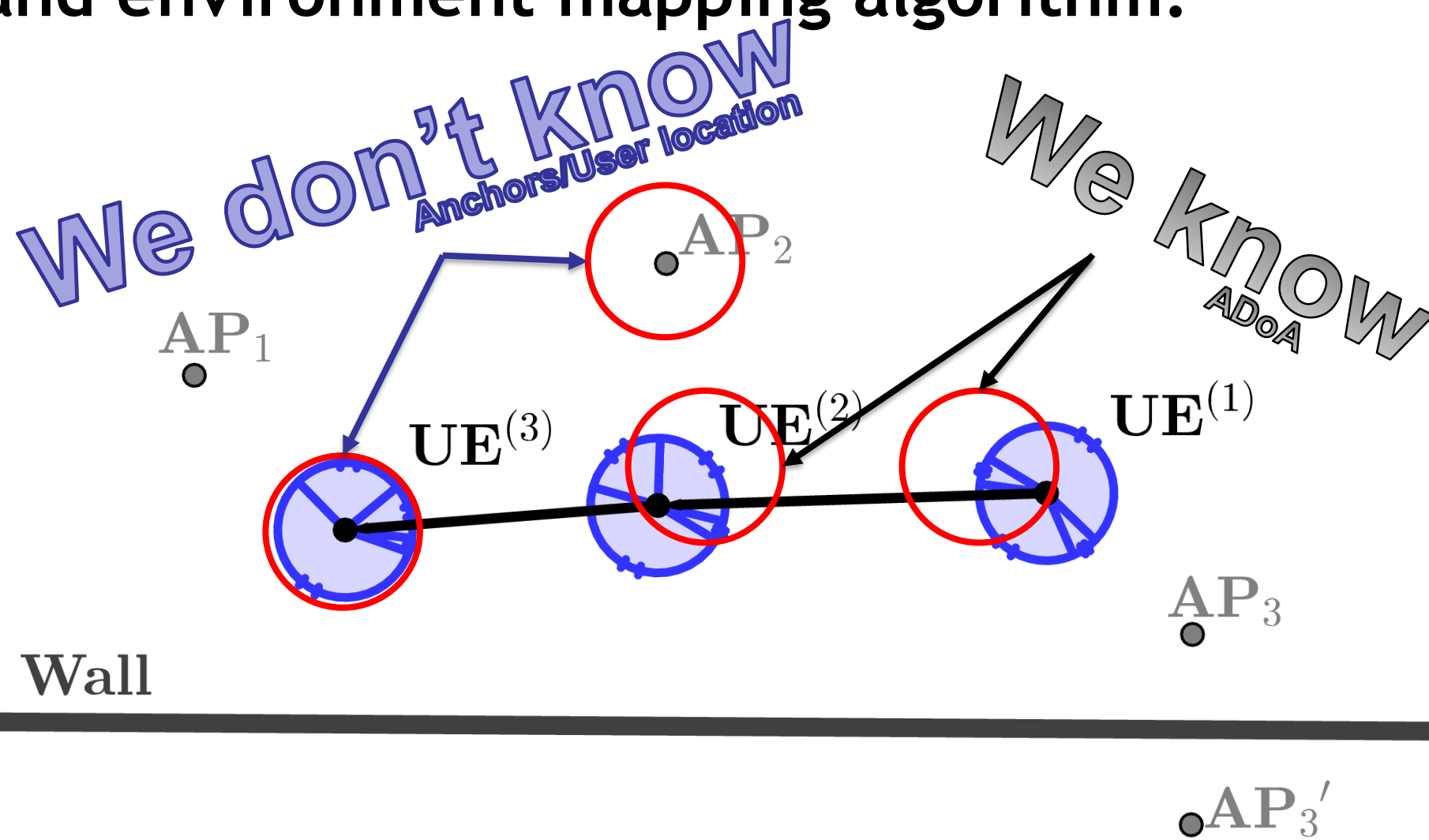
## Introduction



mmWave became a promising solution for 5G.

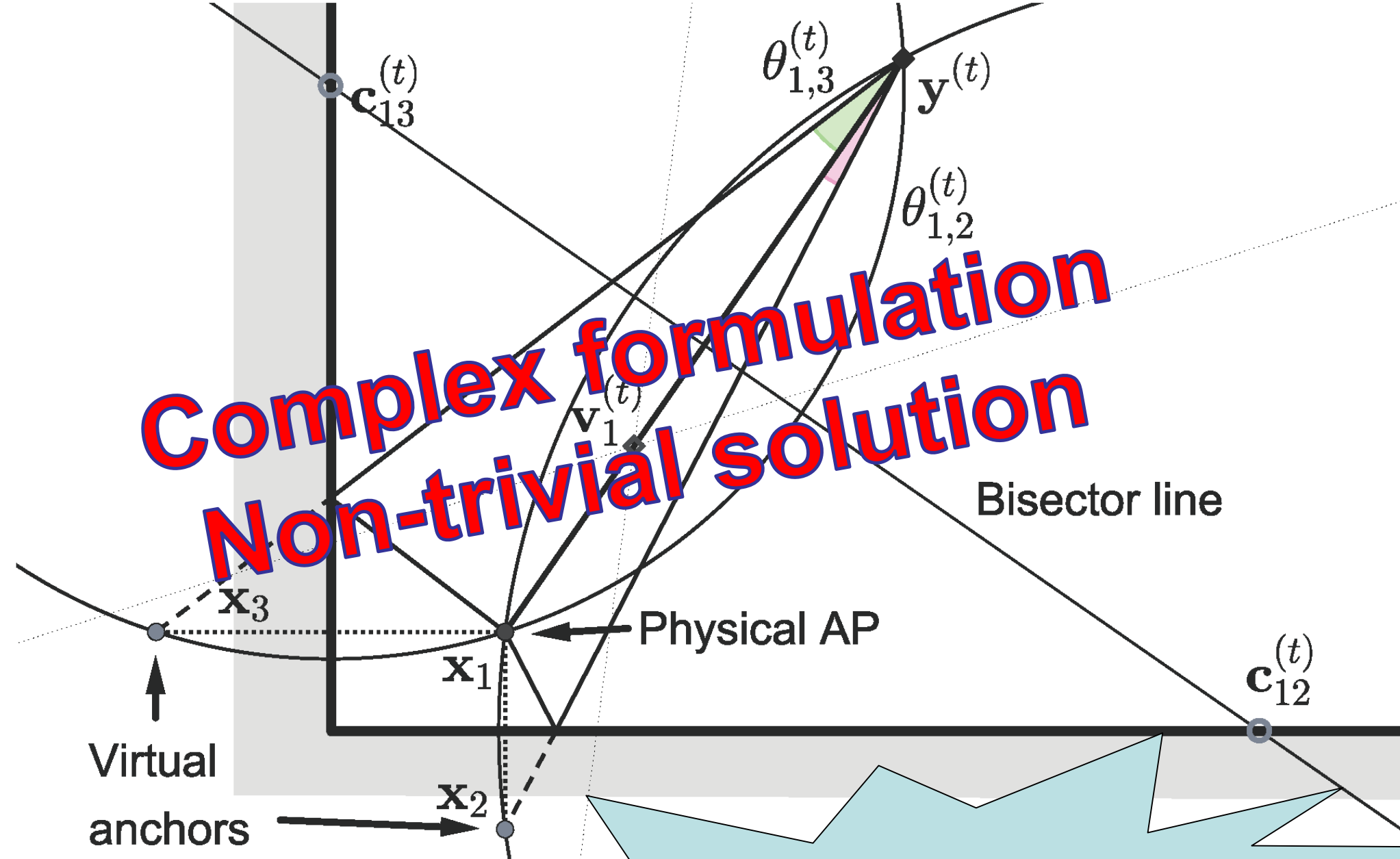
ADoA (Angle Difference of Arrival) is derived from the beam-training.

We want to create a zero-knowledge location and environment mapping algorithm.



## Formulation

### Geometric formulation



### Simplification

Transformation:

$$v_i^{(t)} = \frac{2(y^{(t)} - x_i)}{\|y^{(t)} - x_i\|^2}$$

Yields to a formulation depending on 2 sets of variables  $\{x_i\}$ , the set of Anchors locations and  $\{v_i^{(t)}\}$ , the set of transformed user locations.

If any set is known, the other set can be derived.

This formulation is used to create an iterative refinement algorithm.

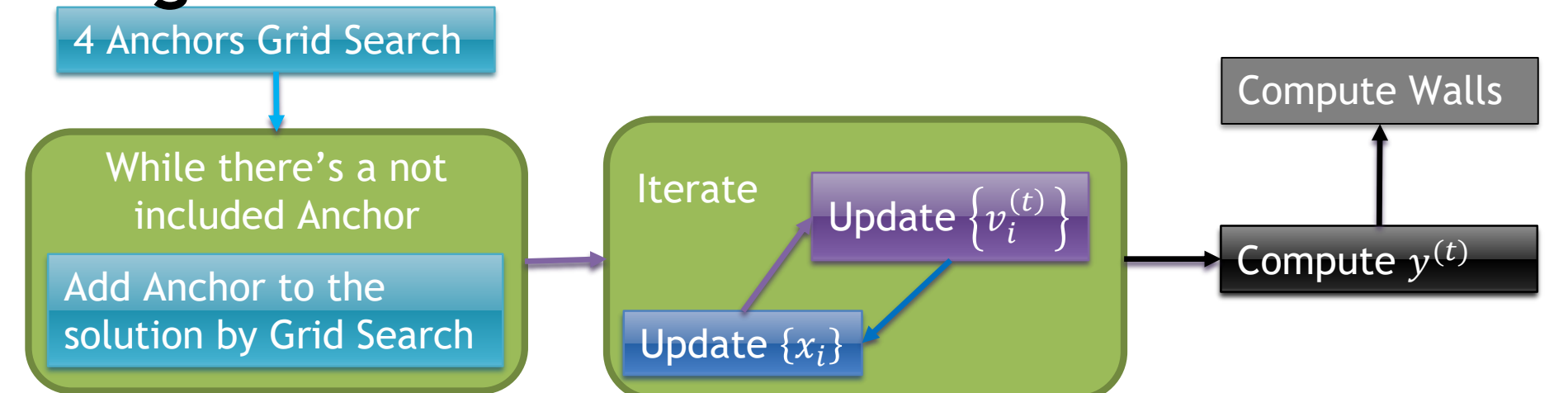
## Algorithm

We create an iterative algorithm to find the solution

### Methods:

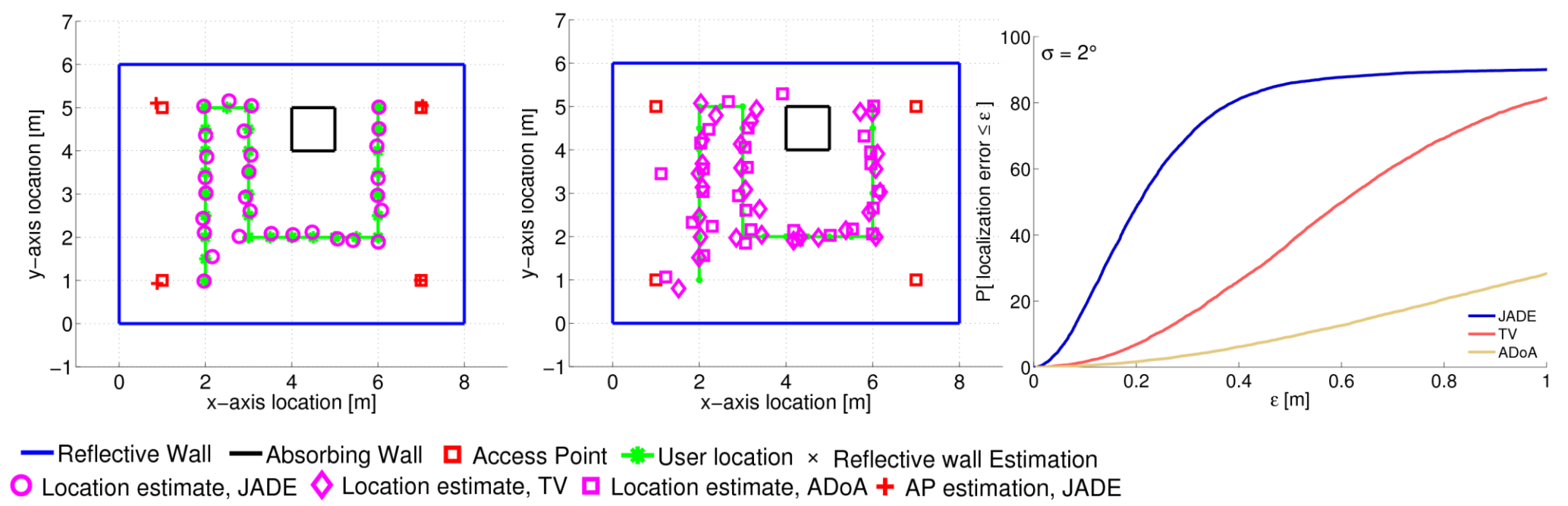
1. Objective function of  $\{x_i\}$  independent from  $\{v_i^{(t)}\}$
2. Compute  $\{v_i^{(t)}\}$  from  $\{x_i\}$
3. Compute  $\{x_i\}$  from  $\{v_i^{(t)}\}$
4. Compute  $\{y^{(t)}\}$  from  $\{x_i\}$  and  $\{v_i^{(t)}\}$

### Algorithm flow:

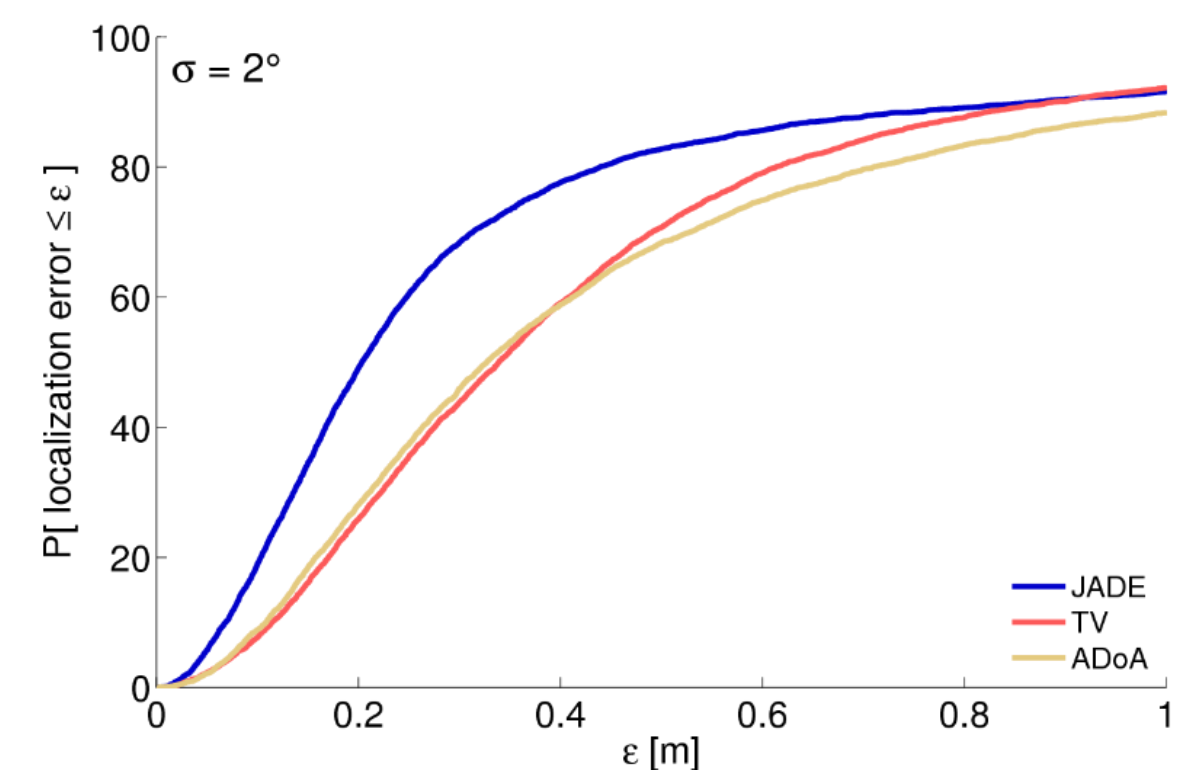
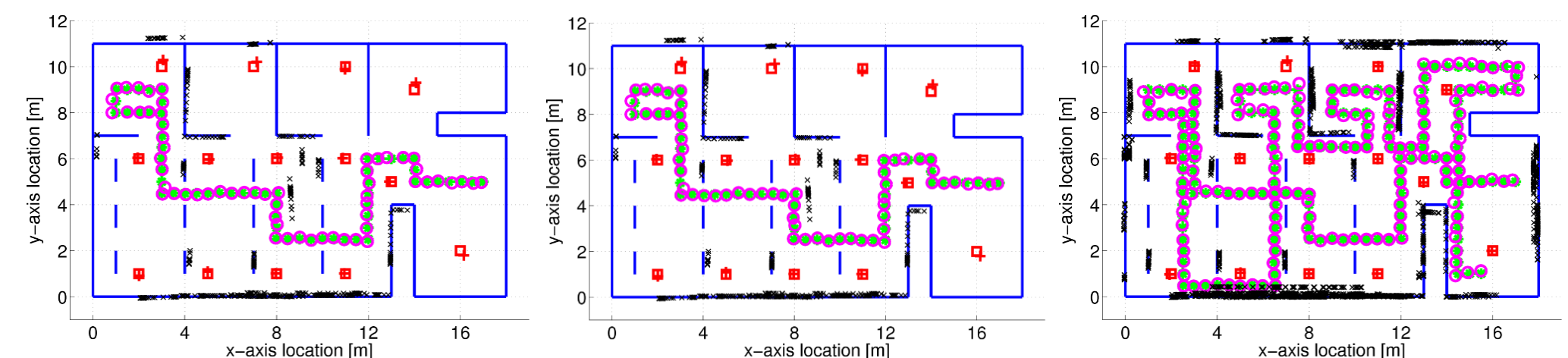


## Results

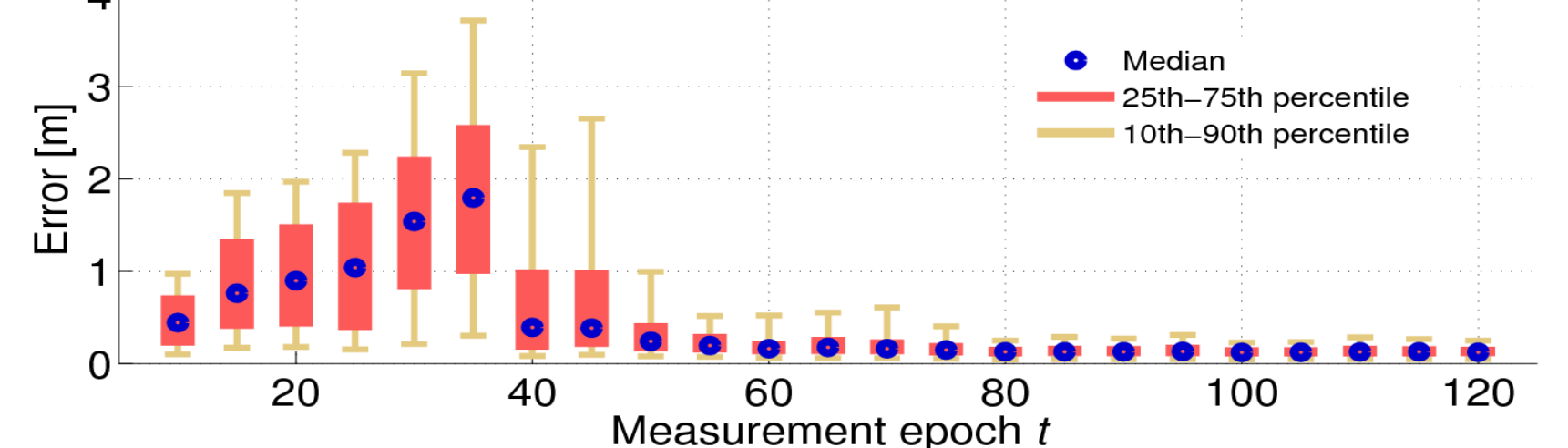
### Path reconstruction



### Path reconstruction + SLAM



### Error evolution



## References

J. Palacios, P. Casari, J. Widmer, "JADE: Zero-Knowledge Device Localization and Environment Mapping for Millimeter Wave Systems", IEEE INFOCOM 2017.

A. Olivier et al., "Lightweight indoor localization for 60-GHz millimeter wave systems", IEEE SECON 2016.